



# Optimisation of surveillance decision

## Application to the diced bacon process

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## Introduction

- In the food industry, food business operators (FBOs) must ensure that “foodstuffs comply with the relevant microbiological criteria” (European regulation (EC) No.2073/2005, Article 3)
- Sampling plan is a tool to assess microbiological contamination in food
- Two-class attribute sampling plan :  $n$  units are sampled in a subpart of the production and analyzed for the presence of a given microorganism

## Introduction

- In the food industry, food business operators (FBOs) must ensure that “foodstuffs comply with the relevant microbiological criteria” (European regulation (EC) No.2073/2005, Article 3)
- Sampling plan is a tool to assess microbiological contamination in food
- Two-class attribute sampling plan :  $n$  units are sampled in a subpart of the production and analyzed for the presence of a given microorganism
- This kind of sampling-plan estimates the prevalence  $\psi$  in a batch :  $\psi$  is estimated with  $x/n$
- Sampling-plan can be used to take a decision about the lot
  - if  $x \leq c$ , a decision is taken
  - if  $x > c$ , another decision is taken.
- How to choose  $n$  and  $c$  properly?

## Decision and uncertainty

- How to make a decision in an uncertain environment?
- Define  $\mathcal{D}$  the set of all possible decisions
- Define  $\Psi$  the set of states of nature  $\psi$  (also called the parameter)
- Use a criterion called the *loss function* defined for all  $(d, \psi) \in \mathcal{D} \times \Psi$  in  $\mathbb{R}^+$
- Every decision  $d$  taken when the state of nature is  $\psi$  has a loss  $L(\psi, d)$

## Decision rule

- The decision  $d$  depends on observation  $x$  through a *decision rule*  $\delta$  defined from the set of observations  $\mathcal{X}$  into  $\mathcal{D}$  :  $\delta : x \mapsto d$
- Aim: find the “best” strategy to associate a decision  $d$  to observation  $x$ , even though  $\psi$  is not fully known
- Remark : when  $\mathcal{D} = \Psi$ ,  $\delta$  is an estimator. Often,  
$$L(\delta(x), \theta) = (\delta(x) - \theta)^2$$

## Bayesian expected loss and risk function

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For all  $x$ , the aim is to find decision  $d$  minimizing  $\rho(d|x)$ . The Bayesian decision rule is :  $\delta : x \mapsto d = \text{Arg min } \rho(d|x)$ .

If, for all  $x \in \mathcal{X}$ ,  $\delta$  minimizes  $\rho$ , it also minimises the *Bayes risk*

$$r(\delta) = \int_{\mathcal{X}} \int_{\Psi} L(\psi, \delta)\pi(\psi|x)f(x)d\psi dx$$

# Predictive analysis

If data  $x$  have not been observed yet:

- Choose the experimental set-up  $e$  which will give  $x_e$
- The best decision rule is the one which minimizes

$$r(\delta_e) = \int \int L(\delta_e(x), \psi) \pi(\psi) f(x|\psi) dx d\psi.$$

## Needed specifications

- 1  $\Psi$  the set of the states of nature  $\psi$  and its distribution  $\pi(\psi)$
- 2 The experimental set-up  $e$
- 3 The set of the observations  $\mathcal{X}$  and its distribution  $f(x|\psi)$
- 4 The set of decisions  $\mathcal{D}$
- 5 The loss function  $L$

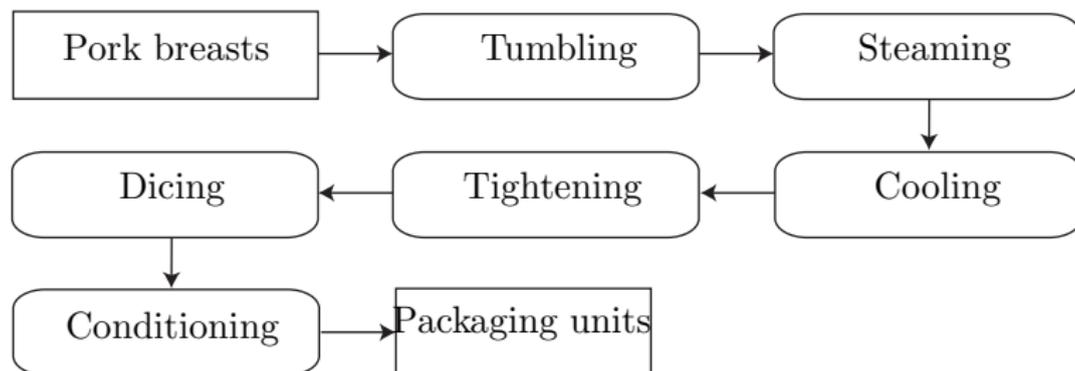
Difficult points: 1, 4 and 5.

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# Process



# Batch

- Statistic *batch*: repetitive behaviour, same probability distribution
- Usual decisions: accepting or rejecting the batch
- In this application: the production batches are not all analyzed, production batch  $\neq$  statistic batch
- Here, the *batch* is a production period of one month

## States of nature, experimental set-up, decisions

- $\psi$  : prevalence of a one-month production,  $\Psi = [0; 1]$  et  $\pi(\psi) = \mathcal{Beta}(a, b)$ 
  - low if  $\psi \in \Psi_0 = [0; \psi_0]$
  - medium if  $\psi \in \Psi_1 = ]\psi_0; \psi_1]$
  - high if  $\psi \in \Psi_2 = ]\psi_1; 1]$
- Experimental set-up : number of observations  $n$  over a period
- Observations : number of positive results  $x$  among  $n$  analyses,  $\mathcal{X} = [0 : n]$ ,  $f(x|\psi, n) = \mathcal{Bin}(n, \psi)$
- Decisions

$$\left\{ \begin{array}{l} d_0, \text{ no corrective action needed} \\ d_1, \text{ a slight corrective action is needed} \\ d_2, \text{ a big corrective action is needed} \end{array} \right.$$

## Posterior and marginal distributions

If  $\psi \sim \text{Beta}(a; b)$  and  $x|\psi \sim \text{Bin}(n, \psi)$ , then  
 $\pi(\psi|x) = \text{Beta}(a + x; b + n - x)$  and

$$\begin{aligned} [x] &= \frac{\pi(\psi)f(x|\psi)}{\pi(\psi|x)} \\ &= \frac{\Gamma(a + b)\Gamma(a + x)\Gamma(b + n - x)\Gamma(n + 1)}{\Gamma(a)\Gamma(b)\Gamma(a + b + n)\Gamma(n - x + 1)\Gamma(x + 1)}, \end{aligned}$$

where  $\Gamma(z) = \int_0^{+\infty} t^{z-1}e^{-t}dt$ .

Remark :  $X$  follows the Polya distribution (probability that a urn has  $a + x$  white balls after  $n$  draws. The urn has initially  $a$  white balls and  $b$  red balls. At each draw a ball is randomly drawn from the urn and is put back along with a new ball of the same color.

## Example of loss function $L$

Assumption: the decisions and the consequences can be quantified in euros

- Decisions taken by the FBO
  - 0 for  $d_0$
  - $C_1$  for  $d_1$
  - $C_2$  for  $d_2$
- Fine to be paid to the client (ex: retailer)
  - 0 if  $\psi \in \Psi_0$
  - $K_1$  if  $\psi \in \Psi_1$
  - $K_2$  if  $\psi \in \Psi_2$
- As  $d_1$  and  $d_2$  should reduce the prevalence
  - the fine when  $d_1$  is taken is reduced by  $1 - \alpha\%$
  - the fine when  $d_2$  is taken is reduced by  $1 - \beta\%$

## Exemple of loss function $L$

Decisions $\psi$	$d_0$	$d_1$	$d_2$
$\psi \in \Psi_0$	$0 + 0 + cn$	$C_1 + cn$	$C_2 + cn$
$\psi \in \Psi_1$	$0 + K_1 + cn$	$C_1 + \alpha K_1 + cn$	$C_2 + \beta K_1 + cn$
$\psi \in \Psi_2$	$0 + K_2 + cn$	$C_1 + \alpha K_2 + cn$	$C_2 + \beta K_2 + cn$

**Table:** Values taken by the cost function  $L$  depending on the decision  $d$  taken by the plant and the prevalence  $\psi$  of the lot.

## Exemple of loss function $L$

The Bayesian expected loss is equal to:

$$\begin{aligned}
 \rho(\delta_n(x) = d|x) &= \int L(\delta_n(x), \psi)\pi(\psi|x, n)d\psi \\
 &= cn + 1_{\delta_n(x)=d_0}(K_1P_1 + K_2P_2)f(x) \\
 &+ 1_{\delta_n(x)=d_1}(C_1 + (\alpha K_1P_1 + \alpha K_2P_2))f(x) \\
 &+ 1_{\delta_n(x)=d_2}(C_2 + (\beta K_1P_1 + \beta K_2P_2))f(x),
 \end{aligned}$$

where  $P_i = \mathbb{P}(\psi \in \Psi_i|x, n)$ ,  $i = 1, 2$ . Decision  $d_0$  is chosen if  $\rho(d_0|x) \leq \rho(d_1|x) \Leftrightarrow x \leq c_1$ .

$$\delta_n(x) = d_0 \quad \Leftrightarrow x \leq c_1$$

$$\delta_n(x) = d_1 \quad \Leftrightarrow c_1 < x \leq c_2$$

$$\delta_n(x) = d_2 \quad \Leftrightarrow x > c_2,$$

## Expert

We asked an expert to estimate costs  $c$ ,  $C_1$ ,  $C_2$ ,  $K_1$  and  $K_2$ .  
The task was the following:

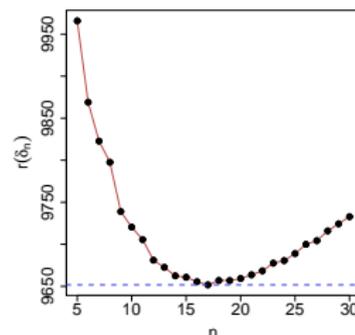
- Define the slight and the big corrections needed to lower the prevalence
- Describe the fines the client charges the plant
- Give a cost to each correction and each kind of fine

$c$	$C_1$	$C_2$	$K_1$	$K_2$	$\alpha$	$\beta$	$\psi_0$	$\psi_1$	$a$	$b$
16	4250	14000	6200	90050	0.3	0.15	0.2	0.6	2	3

# Bayes risk and sampling size

Bayesian risk:

$$\begin{aligned}
 r(\delta_n) &= cn + \sum_{x=0}^{c_1} (K_1 P_1 + K_2 P_2) f(x) \\
 &+ \sum_{x=c_1+1}^{c_2} (C_1 + (\alpha K_1 P_1 + \alpha K_2 P_2)) f(x) \\
 &+ \sum_{x=c_2+1}^n (C_2 + (\beta K_1 P_1 + \beta K_2 P_2)) f(x)
 \end{aligned}$$



The minimum is reached for  $n = 17$ ,  $c_1 = 5$  and

$c_2 = 12$ .

## Conclusion

- Powerful tool to conceptualize the types of decisions taken by a plant
- Elicitation is difficult
- The two most important and difficult issues to be discussed
  - the duration of the period over which it is relevant to consider the prevalence
  - the nature (and costs) of the negative consequences